

FIG WORKING WEEK 2023

28 May - 1 June 2023 Orlando Florida USA

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Werther of the Uncrewed Aircraft System (UAS) Manpus Survey Project at Texas A&M University-Corpus Christi

Authors

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Introduction

- Campus survey project is a collaborative effort funded by TAMUCC Operations and executed by MANTIS lab.
- This was started in 2014.
- The purpose of this initiative is to provide geospatial data support for monitoring and expediting campus improvements and maintenance.



Fig: Location map of Texas A & M University- Corpus Christi







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Background

Ground surveys

> RTK GNSS and Total Stations (TS) for topo, establishing control, line work, etc.

UAS photogrammetric surveys

- > 2D and 3D mapping products
- 2014 to Present: biannually and as needed

Surveys done by students and pilot in command







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Equipment

eBee Sensefly

Started with

eBee RTK

WingtraOne

Transitioned from fixedwing to VTOL platform

Transition from autonomous GNSS to direct georeferencing with PPK onboard



WingtraOne GENII





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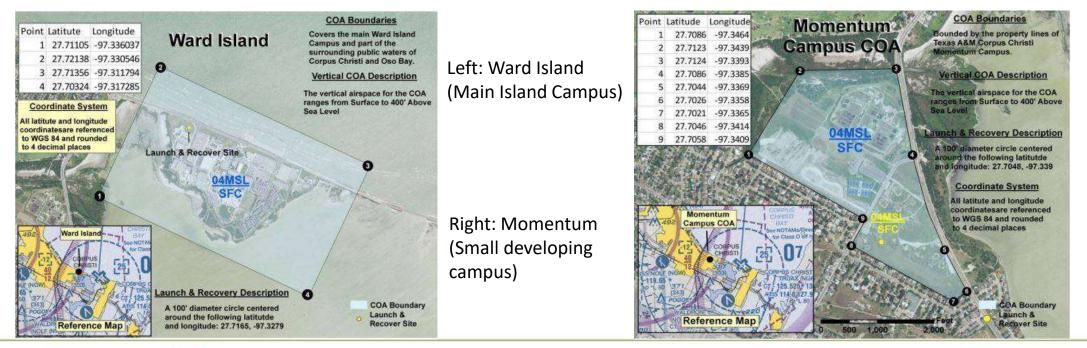




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Authorization process for UAS

To legally operate the UAS, the university had to undergo a lengthy authorization process with the US Federal Aviation Authority(FAA) due to its proximity to the US Naval Air Station; the Certificate of Authorization(COA) was first procured in 2014 and recently renewed in 2022.











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Ground Control Point Network

- TxDOT GNSS Real Time Network
 - Horizontal accuracy up to 2 cm
 - Vertical accuracy up to 4 cm
- Series of GCPs used to check and validate accuracy





Fig: Ground control survey (Left) and Ground control distribution map (Right).







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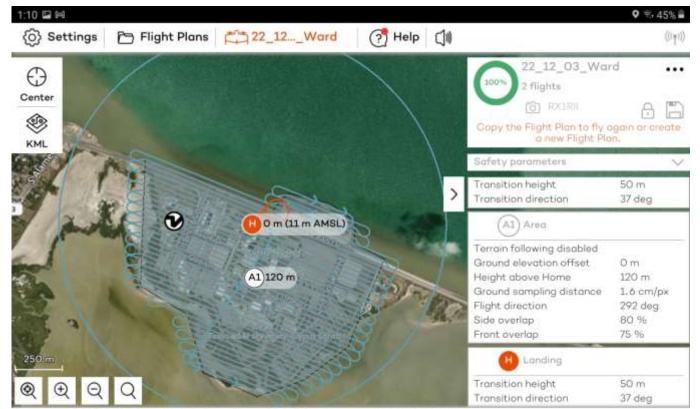
Methodology

Flight Design and Data Collection Sensefly Ebee

- 60% sidelap and 75% endlap
- GSD: 3cm/pix
- Flight height: 107 meters (AGL) WingtraOne Genll
- 80% sidelap and 75% endlap.
- GSD: 0.7cm/pix

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Flight height= 120 meters (AGL)



Distance: 52.02 km Time: 57 min 1 s Total Area: 97.88 ha # Images: 1979 🔊 SRTM

Note: All flights are conducted quarterly to biannually by remote pilot in command/UAS Pilot (Jacob Berryhill).

Fig: Flight plan in WingtraPilot software







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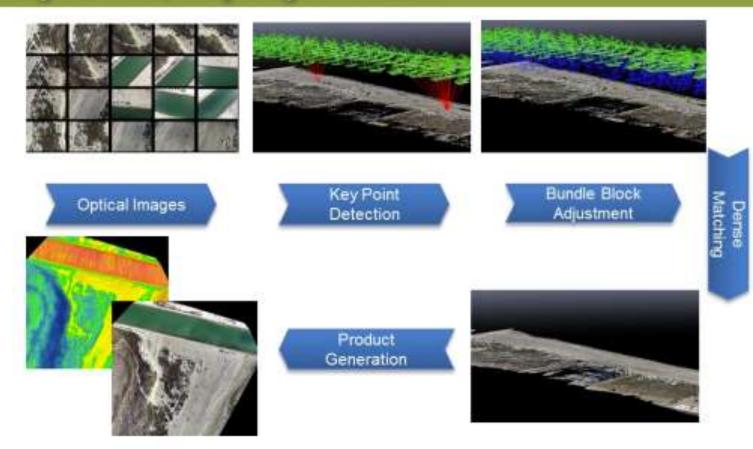


Fig: SfM Processing workflow [3].



UAS - SfM Post-Processing

cloud, DSM, and

orthomosaic.

Generation of 3D point





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Outputs



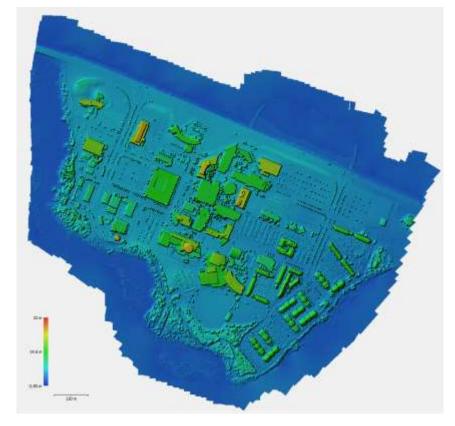


Fig: Colorized 3D point cloud.

Flight Date: December 03, 2022

Fig: DSM







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Outputs



Fig: Orthomosaic.

Flight Date: December 03, 2022

Fig: Point cloud flythrough.









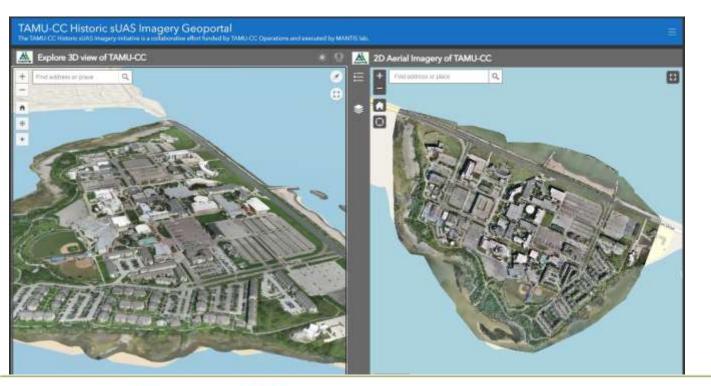
Geoportal

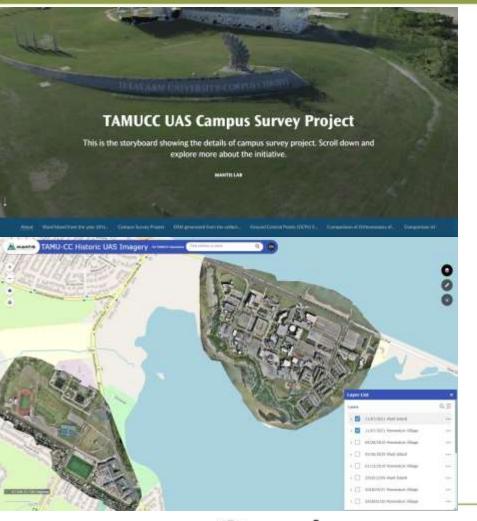
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To visualize the obtained data

- Campus Story map
- Dashboard for 2D and 3D tile layers
- Web mapping application for multitemporal tile layers















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Applications

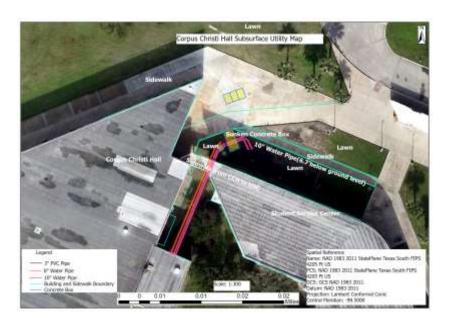


Fig: Subsurface utilities overlaid on UAS orthomosaic.

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Fig: Image showing building change through time.



Fig: Using deep learning models to detect and count palm trees.







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Thank you !!! **Contact Info:** Pratikshya Regmi pregmi@islander.tamucc.edu





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